

## **Temperature Controllers**

## From simple control to advanced control



## Temperature Controller Selection Guide

			Color LCD			Compact	Plug & socket connection
			2347	2349	2346	GBBB 1	
Mode	 el		PXF4	PXF5	PXF9	PXR3	PXR4
		96 × 96			✓		
Pane	l size	48 × 96		✓			
in mn		48 × 48	✓				✓
		48 × 24				✓	
		100–240 V AC	✓	✓	✓	✓	✓
Powe	er supply	24 V DC	✓	✓	✓	✓	<b>✓</b>
		RS-485 (Modbus)	✓	✓	✓	✓	
Comi	munication	RS-485 (Z-ASCII)				<b>✓</b>	
501111		Loader interface	✓	<b>✓</b>	<b>✓</b>	,	
Displa	av	Louder interface	4-digit	4-digit	4-digit	4-digit	4-digit
			=	-	-	Euro-style terminal block,	8-pin or 11-pin, M3.5
Elect	rical conne	ection	M3 screw te	erminal, for wire with	terminal lug	for bare wire or wire ferrule	screw terminal socket
Read	ing accura	су	±0.2% FS	±0.2% FS	±0.2% FS	±0.5% FS	±0.5% FS
Samp	oling time		50 ms	50 ms	50 ms	500 ms	500 ms
	No. of PV	input	1	1	1	1	1
		RTD	✓	✓	✓	✓	✓
		TC	✓	✓	✓	✓	✓
	Sensor	Voltage/current	✓	✓	✓	✓	✓
		Thermistor					
Input		Remote setpoint	✓	✓	✓		
		Current transformer	✓	✓	✓		
	Options	Valve position		✓	✓		
		Digital	≤ 3	≤ 3	≤ 3	≤ 2	
		Relay contact	<b>√</b>	<b>✓</b>	✓	<u>−</u>	✓
		SSR/SSC	✓ (SSR only)	✓ (SSR only)	✓ (SSR only)	<b>✓</b>	<b>✓</b>
	Control	Linear current	✓ (cortonly)	✓ (cort only)	✓ (cortonly)	<b>✓</b>	<b>✓</b>
	output	Linear voltage	· ✓	· •	· ✓	,	•
Output		Motor-operated valve	<b>√</b>	· ✓	<b>✓</b>		
Output		Transfer output (current)	<b>√</b>	·	·	<b>✓</b>	
		Transfer output (voltage)	<b>√</b>	· ✓	· ✓	•	
	Options	Power to transmitter	•	•	•		
		Digital output	≤ 3	≤ 5	≤ 5	≤ 2	≤ 2
		ON-OFF	<b>≤</b> 5	✓	✓	≥∠	✓
	ol .	PID*	✓	<b>✓</b>	<b>✓</b>	<b>✓</b>	<b>✓</b>
Contr			<b>∀</b>	<b>✓</b>	<b>▼</b>	<b>∀</b>	<b>✓</b>
*with auto- tuning		Fuzzy*	<b>∀</b>	<b>✓</b>	<b>∀</b>	<b>∀</b>	<b>∀</b>
		Self tuning	<b>→</b>			<b>V</b>	<b>V</b>
		PID 2*	<b>→</b>	<b>√</b>	<b>✓</b>		
		2-degree-of-freedom PID*				0 -1	0 -1
Others		Ramp soak	64 steps	64 steps	64 steps	8 steps	8 steps
		No. of PID pallettes	8	8	8		
		No. of SVs	8	8	8	4	
		Manual operation	✓	✓	✓		
		User key	1	1	1		
Page			4-9	4-9	4-9	10-13	10-13

Simple	High-end	Thermostat
P. WINNER MAI	18 195 91 2346	17.334
PXE4	PXH9	PXR3
	✓	
✓		
		✓
✓	✓	✓
	<b>✓</b>	
<b>✓</b>	<b>√</b>	4 11 11
4-digit	5-digit	4-digit  Euro-style terminal block,
M3 screw terminal, for	wire with terminal lug	for bare wire or wire ferrule
±0.5% FS	±0.1% FS	±0.5% FS
200 ms	50 ms	2 s
1	2	1
✓	✓	
✓	<b>√</b>	✓
	✓	
		✓
	✓	
	✓	
	≤ 9	
✓	✓	✓
✓ (SSR only)	✓	
	✓	
	✓	
	≤ 2	
_	<b>√</b>	_
≤ 2	≤ 9	≤ 2
<b>√</b>	<b>*</b>	
<b>√</b>	✓	
✓		
<b>✓</b>	✓	
¥		
	64 steps 7	
	7	
	<i>'</i>	
	3	
14-15	16-19	22-23
1 <del>1-</del> 10	10-10	ZZ-ZJ

Module Type Temperature Controllers			
Common Specifications			
Size	30 (W) × 100 (H) × 85 (D) mm		
Power supply	24 V DC		
Accuracy	±0.3% FS		
Sampling time	200 ms		
Communication	RS-485 (MODBUS)		
Loader communication	RS-232C (MODBUS)		
Installation	Rail mount or wall mount		
Control Module (PUMA/PU			
No. of inputs	2 or 4		
Sensor	TC, RTD, voltage/current		
No. of outputs	2 or 4		
Control output signal	Relay contact, current, SSR/SSC		
Control	On/off, PID, heating/cooling		
Auto, manual, remote	Auto, manual, remote		
Options	CT input (4 or 8)		
Event I/O Module (PUME)	)		
No. of DIs	8		
No. of DOs	8		
Output type	Relay contact or transistor		
Analog I/O Module (PUM\	//PUMN/PUMT)		
No. of Als	4		
Input signal	TC, RTD, voltage/current		
No. of AOs	4		
Output signal	4–20 mA DC		
CC-Link Communication Module (PUMCL)			
Programless Communicat	ion with Mitsubishi PLC (PUMCM)		
PROFIBUS Communication Module (PUMCP)			
Ethernet Communication Module (PUMCE)			
Ellieniel Communication			

## Micro-Controller X

## **PXF**

## Superior Versatility and Flexibility for a Wide Range of Applications



#### Fast and Precise control

- Sampling time 50 ms
- · Control 100 ms

### Variety of Control Functions

- On-off
- PID2
- PID
- Two-degree-of-freedom PIDMotor-operated-valve control
- Fuzzy
- Self-tuning

#### **Bus-Powered USB Interface**

For configuration and data viewer software



#### **Universal Input**

- · Accept any signal
- User can change the input type later on

#### Compact Design

• Shallow body with 58-mm depth

### Easy-to-See Display

- Bright and clear color-LCD
- Tallest character height in market
- PV indication in white

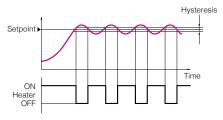




#### **Control Functions**

On-Off Control | Simple and Basic Control

When process value (PV) is below the set value (SV), PXF turns on the output to energize the heater, and vice versa. In this way, PXF keeps the temperature constant by turning the output on and off based on the SV as a threshold.



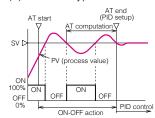
#### **PID Control with Auto Tuning**

#### Typical Control Based on PID Theory

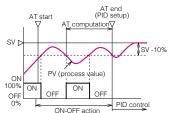
The controller calculates optimal PID parameters. There are 2 types of auto-tuning functions; the standard type (auto-tuning with reference to SV) and the low-SV type (auto-tuning with reference to the value 10% below SV). The low-SV type auto tuning is useful when you want to avoid overshoots. You can also set the PID parameters manually.

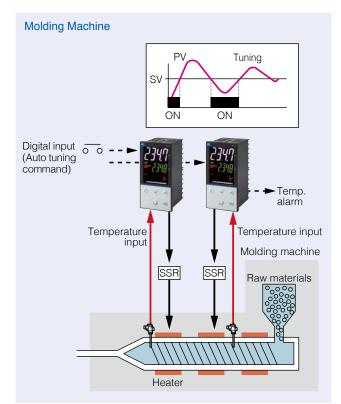
#### **PID Auto Tuning**

(a) Standard type



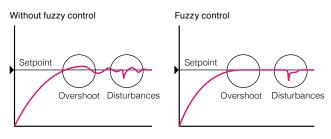
(b) Low-PV type





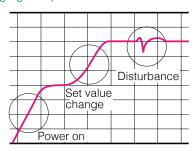
#### **Fuzzy Control with Auto Tuning**

Suppresses Overshoot by Fuzzy Calculation



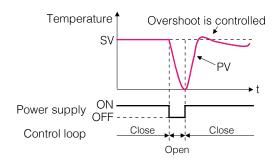
#### **Self Tuning Control**

For Changing Temperature



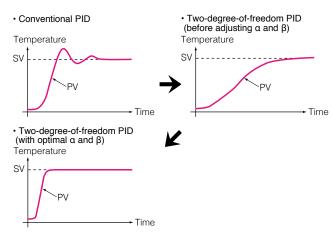
#### **PID2 Control with Auto Tuning**

Suppresses Overshoot and Undershoot



#### **Two-Degree-of-Freedom PID Control with Auto Tuning**

Combined Method for Stable Control





#### Functions for better user experience

#### **Simple Program Control (Ramp Soak Function)**

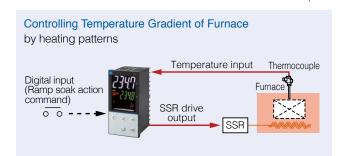
PXF automatically changes SV to the preset values at preset times. You can set up to 64 steps and 15 types of operation patterns. For example, when you bake four kinds of bread, you can divide 64 steps into four patterns to set suitable temperature for each bread. You can start/stop/suspend the operation using a user key, parameter setting, digital input, or communication.

#### ■ Number of steps and patterns

Patterns

Steps

04		
32	2	
16	4	
8	8	Max.
step 1 SV-2/		V-8 SV-9 SV-13 SV-14 SV-15 SV-16
PV TM1s	TM5c	TM16r Time
		i TM16r I Timo



step 1 to 4: pattern 1 step 5 to 8: pattern 2 step 9 to 12: pattern 3 step 13 to 16: pattern 4

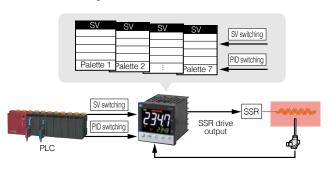
#### **Heating and Cooling Control (option)**

#### **Motorized Valve Control**

#### SV and PID selection

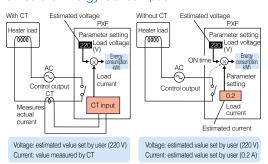
Easy Switching Among 8 Presets

Enables optimum PID setting for changing process, materials, or PV. You can perform SV selection only, PID selection only, or PID selection according to PV.



#### **Simple Watt-Hour Metering Function**

#### Tells You the Energy Consumption



#### **Operating Days Alarm**

#### For Well-Timed Maintenance

Indicator or alarm output alert you when the number of days operated has reached the limit you set.



**Soft Start** 

Saves Energy at Startup

#### **RS-485 Communication (option)**

Multi-drop master function in combination with the twodegree-of-freedom PID control enables synchronous heating control.



- Parameter values can be copied to multiple PXFs simultaneously.
- Communication with PC, HMI, or PLC



#### **Heater Burnout Alarm (option)**

#### Quickly Informs You a Failure

- A current transformer (CT) is required.
- The power supply voltage and the alarm action point must be configured beforehand.

#### **Transfer Output (option)**

Temperature Signals to External Devices

**Alarm Output (option)** Up to 5 Alarms (PXF4: up to 3)

**Digital Input (option)** SV Can be Switched Externally

#### **Remote SV Input (option)**

SV Can be Configured Externally

	_			_ 1
G	eı	ne	116	71

General			
Power supply voltage	100 V (-15%) to 240 V (+10%) AC, 50/60 Hz, or 24 V (±10%) AC/DC		
	Model	100 to 240 V AC	24 V DC/AC
Power consumption	PXF4	10 VA MAX.	5 VA MAX.
	PXF5 & PXF9	13 VA MAX.	8 VA MAX.
Insulation resistance	≥ 20 MΩ (at 500 V DC)		
Withstand voltage	Between the power source and other terminals: 1500 V AC for 1 min Between the relay output and other terminals: 1500 V AC for 1 min Others: 500 V AC for 1 min		
Input impedance	Thermocouple, mV input: ≥ 1 MΩ Current input: ≤ 150 Ω (built-in diode) Voltage input: About 1 MΩ		
Allowable input voltage	DC voltage input: ≤ ±35 V     Current input: ≤ ±25 mA     Thermocouple, RTD, mV input: ≤ ±5 V		
Effect of signal source resistance	Thermocouple, mV input: ±0.3%FS ±1 digit per 100 Ω  Voltage input: ±0.3%FS ±1 digit per 500 Ω		
Allowable wire resistance	RTD: ≤10 Ω per wire		
Input value correction	(a) User adjustment: ±50%FS for each of zero and span point (b) Process value shift: ±10%FS (c) Input filter: 0.0 to 120.0 s (filter is off when set to 0.0) (d) Square root extraction: -0.1 to 105% (OFF if set to -0.1%)		
Noise reduction ratio	Normal mode: 40 dB (50/60 Hz) Common mode: 120 dB (50/60 Hz) Between input and power supply: ±1°C at 220 V AC, 50/60 Hz		
Temperature effect on sensitivity	±0.3%FS per 10°C		

#### Display and keys

Туре	Backlit LCD
Keys	5 embossed keys
Cotents	PV: 11-segment, 4-digit [white] SV: 11-segment, 4-digit [green] Parameter name: 7-segment, 4-digit [orange] Status indicator: ≤ 42
Luminance setting	4 levels
User key	Allows you to switch between: auto/manual, standby on/off, remote SV, ramp/soak, etc.

#### Structure

Installation	Panel mounting
Electrical connection	M3 screw terminal
Case	Material: ABS, PPO     Non-combustibility grade: UL94V-0 equivalent     Color: black
IP rating	Panel front side: IP66, NEMA-4X equivalent (When the panel is mounted using our genuine packing. Not water-proof if mounted closely together.) Body: IP20 equivalent (slits on top and bottom) Terminals: IP00 equivalent
Weight	PXF4: approx. 100 g, PXF5: approx. 170 g, PXF9: approx. 220 g

#### **PV** input

PV input		
No. of inputs	1	
Signal	Thermocouples, RTD, voltage, or current *See a separate table for measurement range.	
Input setting	Programmable scale	
Sampling rate	50 ms	
Indication accuracy (at 23°C)	Thermocouple input: either ±1°C ±1 digit or ±0.3% of indicated value ±1 digit, whichever is larger *except: Thermocouple B: 0 to 400°C: no accuracy assurance Thermocouple B: 0 to 500°C: ±3°C ±1 digit Thermocouples of which measuring range is between -200°C and -100°C: ±2°C ±1 digit  RTD input: ±0.8°C ±1 digit or ±0.2% of indication value ±1 digit, whichever is larger  mV input, voltage input, current input: ±0.3%FS ±1 digit	
Overrange · underrange	Out of the range between -5% and 105% FS (accuracy is not assured between -5 and 0, and between 100 and 105%FS) *Pt (-200°C to 850°C) input, 0–10 V DC input, thermocouple E: Out of the range between -5 to 102% of FS	

#### Remote SV input (option)

No. of inputs	1
	Voltage: 0–5 V DC, 1–5 V DC, 0–10 V DC Current (250 $\Omega$ resistor is required): 0–20 mA DC, 4–20 mA DC
Impedance	Αρρτοχ. 1 ΜΩ
Sampling rate	50 ms

#### **Current transformer input (option)**

Input type	Single phase CT, 1 point For 1 A to 30 A: CTL-6-S-H For 20 A to 100 A: CTL-12-S36-8
Detection range	1 A to 100A
Accuracy	Setpoint ±5%FS
Resolution	0.1A
ON time necessary for detection	≥ 300 ms

#### Digital input (option)

No. of inputs	PXF5 and PXF9: up to 3 PXF4 standard version: 1 PXF4 motorized valve control version: 3			
Switch	Volt-free contact or transistor			
Contact capacity	5 V DC, about 2 mA (per point)			
Input judgment	ON voltage: 2 V DC or lower OFF voltage: 3 V DC or higher			
Input pulse width	≥ 50 ms			
Functions	Remote mode selection, SV changeover, control standby, AT startup, timer startup, alarm unlatch, program selection, start/stop/reset, PID switching (normal/reverse), etc.			

#### Valve position feedback signal input (option for PXF5 and PXF9 only)

Resistance range	100 $\Omega$ to 2.5k $\Omega$ , three-wire
Resolution	0.5% FS
Accuracy	±1.0%FS
Temperature effect on sensitivity	±0.5%FS per 10°C
Burnout function None	

#### Alarm output (option)

No. of points	Relay contact Shared COM: PXF4: ≤3, PXF5 & PXF9: ≤5 Independent COM: PXF4: ≤2, PXF5 & PXF9: ≤3		
Contact	Contact structure: SPST-NO     Contact capacity: 250 V AC / 30 V DC, 1A (resistive load)     Minimum ON/OFF current: 10 mA (5 V DC)     Mechanical life: ≥ 20 million operations (100 operations/min)     Electrical life: ≥ 100,000 operations (rated load)		
Functions	Alarm output, main unit control mode output, program status output, control output 1 and 2, etc.		
Output cycle	100 ms		

#### Alarm

No of alarmo	PXF4: ≤ 3 PXF5 & PXF9: ≤ 5 (depends on the number of DO)		
Alarm type	Process value (upper limit/lower limit, absolute/deviation, range), device error, etc.(non-excitation, delay, latch, timer function available)		
Heater current alarm function (option)	Current transformer (CT) is to be prepared separately Detectable range: 1 A to 100 A Detected current resolution: 0.1A Setting resolution: 0.1A Hysteresis: 0.0 to 100.0 A		

#### Transfer output (option)

No. of points	1
Туре	0-20 mA DC / 4-20 mA DC / 0-5 V DC / 1-5 V DC / 0-10 V DC / 2-10 V DC  • Guaranteed output range: 0-21 mA DC / 0-10.5 V DC  • Accuracy: ±0.2%FS (±5%FS at 1 mA or smaller)  • Resolution: ≥ 10,000  • Load resistance: ≤ 500 Ω (current), ≥ 10 kΩ (voltage)
Output cycle	100 ms
Contents	PV, SV, DV, MV
Additional function Scaling function	



#### **Control output**

Control output	
No. of points	≤ 2
Туре	<ol> <li>Relay contact output (SPST-NO)</li> <li>Proportional cycle: 1 to 150 s</li> <li>Contact capacity: 250 VAC / 30 VDC, 3A (resistive load)</li> <li>Minimum ON/OFF current: 10 mA (5 V DC)</li> <li>Mechanical life: ≥ 20 million operations (100 operations/min)</li> <li>Electrical life: ≥ 100,000 operations (rated load)</li> <li>Relay contact output (SPDT)</li> <li>Proportional cycle: 1 to 150 s</li> <li>Contact capacity: 250 VAC / 30 VDC, 5A (resistive load)</li> <li>Mechanical life: ≥ 50 million operations (100 operations/min)</li> <li>Electrical life: ≥ 100,000 operations (rated load)</li> <li>SSR drive output</li> <li>Proportional cycle: 1 to 150 s</li> <li>ON voltage: 12 V DC (between 10.7 and 13.2 V DC)</li> <li>OFF voltage: ≤ 0.5 V DC</li> <li>Maximum current: 20 mA DC</li> <li>Load resistance: ≥ 600 Ω</li> <li>Current output (0-20 mA DC / 4-20 mA DC)</li> <li>Accuracy: ±5%FS</li> <li>Load resistance: ≤ 500 Ω</li> <li>Voltage output (0-5 V DC / 1-5 V DC / 0-10 V DC / 2-10 V DC)</li> <li>Accuracy: ±5%FS</li> <li>Load resistance: ≥ 10 kΩ</li> <li>Motorized valve control output</li> <li>Contact structure: 2 SPST-NO contacts without interlock circuit</li> <li>Contact acpacity: 250 VAC / 30 VDC, 3A (resistive load)</li> <li>Minimum ON/OFF current: 100 mA (24 V DC)</li> <li>Mechanical life: ≥ 100,000 operations (rated load)</li> </ol>

#### Control

Control				
Control type				
On-off				
PID				
Fuzzy PID	Can be used in heating and cooling dual control. PID parameters are auto tuned.			
PID2	'			
Self tuning				
Two-degree-of-freedom PID	PID parameters are auto tuned.			
Position proportional PID (servo)	PXF4: without position feedback PXF5 and PXF9: with position feedback Full stroke time: ≥ 30 s			
Control mode	Auto/Manual/Remote  * In manual mode, on/off control is performed with 100% MV or 0% MV.  Mode changeover:  • Auto ↔ Manual: Balanceless • bumpless  • Auto/Manual→Remote: Balance • bumpless  • Auto/Manual←Remote: Balance • bumpless			
Parameters				
Proportional band (P)	0.1% to 999.9%			
Integration time (I)	0 to 3200 s (invalidated when I = 0)			
Differential time (D)	0.0 to 999.9 s (invalidated when D = 0)			
Control cycle	100 to 900 ms (in 100 ms), 1 to 99 s (in seconds)			
Anti-reset windup	set windup 0 to 100% of measurement range			
Hysteresis band	50% of measurement range (for on/off action only)			
Number of SV and PID patterns	8: Changed by any of parameter setting, digital input, communication, user function keying, zone change.			

#### Measurement range

Input signal		Code (PvT)	Range [°C]	Resolution [°C]
		PT1	0.0 to 150.0	0.1
		PT2	0.0 to 300.0	0.1
		PT3	0.0 to 500.0	0.1
RTD	Pt 100	PT4	0.0 to 600.0	0.1
HID	Pt 100	PT5	-50.0 to 100.0	0.1
		PT6	-100.0 to 200.0	0.1
		PT7	-199.9 to 600.0	0.1
		PT8	-200 to 850	1
	0 to 5 V DC	0-5V		
DC voltage	1 to 5 V DC	1-5V	-1999 to 9999 (Range where scaling is al- lowed)	
	0 to 10V DC	0-10		
	2 to 10V DC	2-10		-
	0 to 100mV DC	MV		
DC current	0 to 20 mA DC	0-20		
	4 to 20 mA DC	4-20		

#### RS-485 communication

Modbus RTU, half-duplex bit serial, asynchronous communication				
Serial characteristics	Data bits: 8 bits. Parity: odd, even, none Baud rate: 9600 bps, 19200 bps, 38.4 kbps, 115.2 kbps			
Connection	≤ 32 units			
Communication distance	≤ 500 m (total connection length)			
Additional function	Multidrop master function The function in which slave devices can be operated by a master device by connecting several temperature controllers. Programless communication The function in which a temperature controller can be connected to a PLC without program. Supported PLCs: Mitsubishi PLC Q series Siemens PLC S7 series			

O	
/ Ither	function

Other functions			
Ramp soak	64 steps × 1 pattern, 32 steps × 2 patterns, 16 steps × 4 patterns, or 8 steps × 8 patterns (1 step = 2 segments)  - Control option: control by digital input or status output by digital output  - Time setting: "Hour, Minutes" or "Minutes, Seconds"  - Guaranteed soak  - Repeat action  - PV start  - Delay start  - Power failure recovery  - Memory backup on EEPROM		
Data backup at power outage	on non-volatile memory		
Self-diagnosis	by watchdog timer		
Password three-level password			
Simple watt-hour metering function	By connecting a current transformer (to be prepared separately), electric power consumption of the heater can be displayed. (Electric power is calculated based on the fixed voltage value you set.)     Current transformer (CT) is to be prepared separately.     Current detection range: 1 A to 100 A		
Operating days alarm	<ul> <li>Indicates the number of days the controller has been operated and activates alarm output (optional) when it exceeds the setpoint.</li> <li>Useful for preventive maintenance because it let you know the appropriate time for maintenance work.</li> </ul>		

#### Operation and storage conditions

Operation and storage conditions				
Operating temperature	-10°C to 50°C			
Storage temperature	-20°C to 60°C			
Humidity	≤ 90% RH (no condensation)			
Warm-up time	≥ 30 min			
Vibration	during transportation: ≤ 9.8 m/s² (1 G)			
Impact	during transportation: ≤ 294 m/s² (30 G)			

Input signal		Code (PvT)	Range [°C]	Resolution [°C]
	J	J1	0.0 to 400.0	0.1
		J2	-20.0 to 400.0	0.1
		J3	0.0 to 800.0	0.1
		J4	-100 to 1000	1
		K1	0 to 400	0.1
	К	K2	-20.0 to 500.0	0.1
	K	K3	0.0 to 800.0	0.1
		K4	-200 to 1300	1
	R	R	0 to 1700	1
	В	В	0 to 1800	1
Thermocouple	S	S	0 to 1700	1
mermocoupie	Т	T1	-199.9 to 200.0	0.1
		T2	-199.9 to 400.0	0.1
	E	E1	0.0 to 800.0	0.1
		E2	-150.0 to 800.0	0.1
		E3	-200 to 800	1
	L	L	-100 to 850	1
	U	U1	-199.9 to 400.0	0.1
		U2	-200 to 400	1
	N	N	-200 to 1300	1
	W	W	0 to 2300	1
	PL-II	PL-2	0 to 1300	1

### **Ordering Code**

#### **PXF4 Standard Type**

Digit	Specification	Code
1-4	⟨Front dimensions W x H⟩	
1-4	48 × 48mm	PXF4
5	_	А
	⟨Control output 1⟩	
	Relay contact (SPST) *1	A
6	Relay contact (SPDT) *1	В
U	SSR drive output	С
	Current output	E
	Voltage output	Р
	⟨Control output 2⟩	
	None	Y
	Relay contact (SPST)	A
7	SSR drive output	С
·	Current output	E
	Voltage output	Р
	Transfer output (current)	R
	Transfer output (voltage)	S 2
- 8	⟨Revision code⟩	
	〈Alarm output〉	
	None	0
9	1 point	1
Ū	2 points	F
	3 points	M
	2 points (independent common)	J
	Power supply voltage / instruction manual	
	100 to 240 V AC, Japanese & English	Y
	100 to 240 V AC, English	V
10	100 to 240 V AC, Chinese & English	W
	24 V AC/DC, Japanese & English	A
	24 V AC/DC, English	В
	24 V AC/DC, Chinese & English	D
	(Option)	
	None	1
	RS-485 communication	M
11	Digital input (DI1)	S
	RS-485 communication + Digital input (DI1)	V
	RS-485 communication + Remote SV input *2	K
10	RS-485 communication + CT input *3	J
12	_	00
13		

\*1: Not available for the 7th code "C", "E", "P", "R", "S". However, if you want to order the 6th code "A" (SPST relay contact for the control output 1) and the 7th code "R" or "S" (current/ voltage re-transmission output for the control output 2), specify the model as follows:

\*\*PXFAAA\*\* \$\frac{18}{12}\$2-1111002

\*2: When using current for the remote SV input, add a 250-ohm resistor to the input terminal.
\*3: When using the CT input for heater burnout alarm, add one alarm output for it in the 9th code.

#### PXF5 & PXF9 Standard Type

Digit	Specification	Code
	⟨Front dimensions W x H⟩	
1-4	48 × 96 mm	PXF5
	96 × 96 mm	PXF9
5	-	Α
	⟨Control output 1⟩	
	Relay contact (SPST)	Α
6	Relay contact (SPDT)	В
U	SSR drive output	С
	Current output	E
	Voltage output	Р
	⟨Control output 2⟩	
	None	Υ
	Relay contact (SPST)	Α
7	SSR drive output	С
,	Current output	E
	Voltage output	P
	Transfer output (current)	R
	Transfer output (voltage)	S 2
- 8	⟨Revision code⟩	
	〈Alarm output〉	
	None	0
9	1 point	1
3	2 points	F
	3 points	M
	2 points (independent common)	J
	⟨Power supply voltage / instruction manual⟩	
	100 to 240 V AC, Japanese & English	Υ
	100 to 240 V AC, English	V
10	100 to 240 V AC, Chinese & English	W
	24 V AC/DC, Japanese & English	Α
	24 V AC/DC, English	В
	24 V AC/DC, Chinese & English	D
	⟨Option⟩	
	None	1
	RS-485 communication	M
11	Digital input (DI 1 and DI2)	T
- ''	Remote SV input + Digital input (DI3) *1	Н
	CT input + Digital input (DI1) *2	G
	RS-485 communication + Digital input (DI1)	V
	RS-485 + Digital input (DI3, DI4, DI5) + Auxiliary alarm output (AL4, AL5)	С
12	_	00
13		00

\*1: When using current for the remote SV input, add a 250-ohm resistor to the input terminal.
\*2: When using the CT input for heater burnout alarm, add one alarm output for it in the 9th

#### **PXF4 Motorized Valve Control Type**

Digit	Specification	Code
1-4	⟨Front dimensions W x H⟩ 48 × 48mm	
5	_	А
6	(Control output 1) Motorized valve control output (without PFB input)	
7	⟨Control output 2⟩ None	Υ
8	⟨Revision code⟩	2
9	<a href="Alarm output"> <a hr<="" th=""><th>0 1 F J</th></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a></a>	0 1 F J
10	⟨Power supply voltage / instruction manual⟩ 100 to 240 V AC, Japanese & English 100 to 240 V AC, English 100 to 240 V AC, Chinese & English 24 V AC/DC, Japanese & English 24 V AC/DC, English 24 V AC/DC, Chinese & English	Y V W A B
11	(Option) None Digital input (DI 1, 2, 3) RS-485 communication + Digital input (DI1)	1 D V
12	_	00

#### Separate order items

Current transformer	1 A to 30A	ZOZ*CCTL-6-S-H
Current transformer	20 to 100A	ZOZ*CCTL-12-S36-8
Terminal cover		ZZPPXR1-A230
Parameter loader interface cable		ZZP*TQ501923C3
Shunt resistor (250 Ω±0.1%)		ZZPPXR1-A190
Panel mounting adapter for replacement from PXR7 to PXF4		ZZP*TQ502732C1
ranermounting adapter for replacement from FAR7 to FAF4		ZZF # TQ302/32CT

#### **PXF5 & PXF9 Motorized Valve Control Type**

Digit	Specification	Code
	⟨Front dimensions W x H⟩	
1-4	48 × 96 mm	PXF5
	96 × 96 mm	PXF9
5	-	Α
	⟨Control output 1⟩	
6	Motorized valve control output (without PFB input)	S
	Motorized valve control output (with PFB input)	V
7	⟨Control output 2⟩	
	None	Y
8	⟨Revision code⟩	2
	〈Alarm output〉	
	None	0
9	1 point	1
J	2 points	F
	3 points	M
	2 points (independent common)	J
	〈Power supply voltage / instruction manual〉	
	100 to 240 V AC, Japanese & English	Υ
	100 to 240 V AC, English	V
10	100 to 240 V AC, Chinese & English	W
	24 V AC/DC, Japanese & English	Α
	24 V AC/DC, English	В
	24 V AC/DC, Chinese & English	D
	⟨Option⟩	
11	None	1
	RS-485 communication + Digital input (DI1, DI2, DI3)	U
12	_	00
13		

#### Separate order items

Current transformer	1 A to 30A	ZOZ*CCTL-6-S-H
Current transformer	20 to 100A	ZOZ*CCTL-12-S36-8
Terminal cover *1		ZZPPXF1-B100
Parameter loader interface cable		ZZP*TQ501923C3
Shunt resistor (250 Ω±0.1%)		ZZPPXR1-A190

\*1: For PXF9, two covers are necessary for one unit.

#### Scope of delivery

Controller, panel mounting adapter, water-proof packing, instruction manual

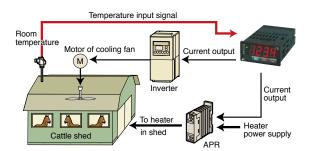
# Micro-Controller X PXR



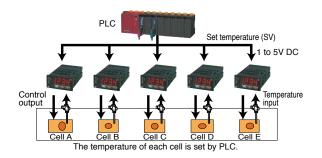
### Compact Type and Plug & Socket Connection type

- Heating and cooling control
- Front waterproof structure
- Sampling time 500ms
- 2 DIs + 2 DOs available
- Options: alarm, RS-485 communication, transfer output, ramp soak

#### **Energy-efficient air conditioning system**



#### Optimal control of multiple heating devices

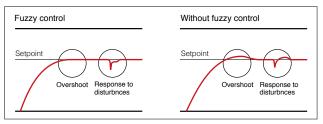


## PXR3 and PXR4

#### **Control Functions**

#### **Auto-Tuned Fuzzy Control**

PXR monitors the process temperature and suppress overshoot and effect of external disturbances based on the fuzzy logic, without increasing the startup time.

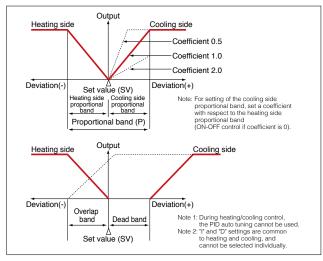


#### **On-Off Control**

The temperature controller keeps the temperature stable by turning on the power supply for a heater when the process value is lower than the setpoint, and turning it off when the process value is higher than the setpoint. The controller works in on-off control if you set the parameter P to zero.

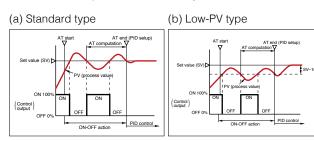
#### **Heating / Cooling Control (option for PXR3)**

By using two control outputs, you can control both heating process and cooling process with a single controller.



#### **Auto-Tuned PID Control**

The controller calculates optimal PID parameters. There are 2 types of auto-tuning functions; the standard type (auto-tuning with reference to SV) and the low-SV type (auto-tuning with reference to the value 10% below SV). The low-SV type auto tuning is useful when you want to avoid overshoots. You can also set the PID parameters manually.



#### **Self-Tuned PID Control**

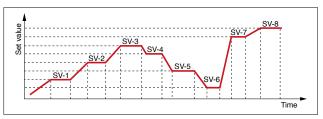
The controller tunes PID parameters when necessary; for example, at startup of the equipment, when the setpoint is changed, and/or the process temperature changed due to disturbance.

External disturbance Set value change

Note: For some objects to control, PID values could not be optimized.

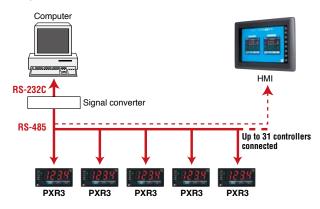
#### **Ramp Soak Control (option)**

PXR automatically changes the setpoint to the preset values at preset times. You can set up to 64 steps and 15 patterns.



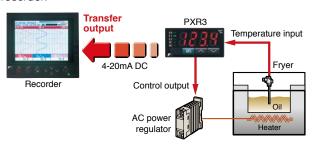
#### **RS-485 Communication (option for PXR3)**

Allows the temperature controller to communicate with a PC, PLC, or HMI.



#### **Transfer Output (option for PXR3)**

PXR3 can send SV, PV, MV, or deviation of PV and SV, as 4–20 mA signal to an external device such as a recorder. Allows you to save the cost for a temperature sensor for recorder.



## PXR3 and PXR4

## Specifications

General		
Power supply voltage	100 V (-15%) to 240 V (+10%) AC, 50/60 Hz, or 24 V (±10%) AC/DC	
Power consumption	100 V AC: ≤ 6 VA (PXR3), ≤ 8 VA (PXR4) 220 V AC: ≤ 8 VA (PXR3), ≤ 10 VA (PXR4) 24 V AC/DC: ≤ 8 VA (PXR3), ≤ 10 VA (PXR4)	
Insulation resist- ance	≥ 20 MΩ (at 500 V DC)	
Withstand voltage	Between the power source and the ground terminal: 1500 V AC for 1 min Between the power source and others: 1500 V AC for 1 min Between the ground and relay outputs: 1500 V AC for 1 min Between the ground and alarm outputs: 1500 V AC for 1 min Others: 500 V AC for 1 min	
Input impedance	Thermocouple, mV input: $\geq 1 \text{ M}\Omega$ Current: 250 $\Omega$ (external resistor) Voltage: $\geq 450 \text{ k}\Omega$	
Allowable signal source resistance	Thermocouple: $\leq$ 100 $\Omega$ Voltage: $\leq$ 1 k $\Omega$	
Allowable wire resistance	RTD: ≤ 10 Ω per wire	
Input value correction	Process value shift: ±10% FS Input filter: 0 to 900.0 s settable in 0.5 s steps (first order lag filter)	
Noise reduction ratio	Normal mode noise (50/60 Hz): ≥ 50 dB Common mode noise (50/60 Hz): ≥ 140 dB	
Display and keys	6	
Туре	LED, 3 keys	
Cotents	SV and PV: 4 digits, 7-segment (PXR3: SV/PV switching, PXR4: SV/PV independent display) Status indicator: control output, alarm	
Structure		
Installation	Panel flush mounting Can be mounted to rail/wall by using the DIN rail mounting adapter available as option.	
Electrical connection	PXR3: euro-style terminal PXR4: 8-pin or 11-pin, M3.5 screw terminal socket	
Case	Plastic (non-combustible grade UL94V-0 equivalent), black	

Front waterproof structure: NEMA4X (IP66 equivalent)
"When mounted on panel with our genuine packing. Waterproof
feature unavailable in close mounting of multiple units.
Rear case: IP20

Approx. 150 g (PXR3), 200 g (PXR4)

PV input		
No. of inputs	1	
Signal	Thermocouples, RTD, voltage, or current *See a separate table for measurement range.	
Sampling rate	0.5 s	
Indication accuracy(at 23°C)	Thermocouple: $\pm (0.5\%$ of measuring range) $\pm 1$ digit $\pm 1^{\circ}$ C For thermocouple R at 0 to $500^{\circ}$ C: $\pm (1\%$ of measuring range) $\pm 1$ digit $\pm 1^{\circ}$ C For thermocouple B at 0 to $400^{\circ}$ C: $\pm (5\%$ of measuring range) $\pm 1$ digit $\pm 1^{\circ}$ C RTD, voltage/current: $\pm (0.5\%$ of measuring range) $\pm 1$ digit	
Burnout	In the thermocouple input version or the RTD input version, a user can select either the upper or the lower limit to which the control output should go when a sensor burnout occurs.	
Digital input (opt	ion for PXR3)	
No. of inputs	≤ 2	
Switch	Volt-free contact or transistor	
Contact capacity	5 V DC, about 2 mA (per point)	
Input judgment	ON voltage: ≤ 2 V DC OFF voltage: ≥ 3 V DC	
Input pulse width	≥ 0.5 s	
Functions	Set value (front SV, SV1 to 3) changeover Control action start / stop Ramp/soak action start / reset Auto tuning start / stop Alarm latch cancel Alarm on- or off-delay timer: setting range 0–9999 s in 1 s steps	
Alarm output		
No. of alarms	≤ 2	
Alarm type	Absolute alarm, deviation alarm, zone alarm with upper and lower limits for each Hold function available Alarm latch, Excitation/non-excitation selecting function provided	
Alarm ON-delay	Delay setting 0 to 9999 s settable in 1 s steps	
Contact	Relay contact (SPST-NO): 220 VAC / 30 VDC, 1 A (resistive load) Mechanical life: 10 million operations (no load) Electrical life: 100,000 operations (rated load) Electrical life: 100,000 operations (rated load) Minimum switching current: 10 mA (5 V DC). Output cycle: 0.5 s	

#### **Control output**

IP rating

Weight

·	Control output 1	Control output 2 (option for PXR3, for cooling/heating control)
Туре	Select one of the followings:  • Relay contact (PXR3: SPST-NO, PXR4: SPDT): 220 VAC / 30 VDC, 3A (resistive load) Mechanical life: 10 million operations (no load) Electrical life: 100,000 operations (rated load) Minimum switching current: PXR3: 10 mA (5 VDC), PXR4: 100 mA (24 VDC)  • SSR / SSC drive (voltage pulse): ON: PXR3: 12-16 V DC, PXR4: 17-25 VDC OFF: ≤ 0.5V DC Maximum current: 20 mA  • 4-20 mA DC: Allowable load resistance: PXR3: 100-500 Ω, PXR4: ≤ 600Ω	Select one of the followings:  • Relay contact: SPST-NO, 220 VAC / 30VDC, 3A (resistive load)  Mechanical life: 10 million operations (no load)  Electrical life: 100,000 operations (rated load)  Minimum switching current: 10 mA (5 V DC)  • SSR/SSC drive (voltage pulse):  ON: 12-16 V DC  OFF: ≤ 0.5V DC  Maximum current: 20 mA  • 4 to 20 mA DC: Allowable load resistance: 100–500 Ω
Control type	PID control (with auto tuning, self-tuning) Fuzzy control (with auto tuning)	PID control (with auto tuning)
Parameters	On/off action if $P=0$ . Proportional action when I, $D=0$ .	P,I,D=0: ON/OFF action (without dead band) for heating and cooling I,D=0: Proportional action
Proportional band (P)	0 to 999.9% of measuring range settable in 0.1% steps	Heating side: 0 to 999.9 % of measuring range Cooling side: Heating side "P" × cooling side coefficient Cooling side proportional band coefficient: 0 to 100.0 On/off action if P=0
Integration time (I)	0 to 3200 s settable in 1 s steps	0 to 3200 s
Differential time (D)	0 to 999.9 s settable in 0.1 s steps	0 to 999.9 s
Proportional cycle	1 to 150 s settable in 1 s steps Only for relay contact output or SSR/SSC drive output	1 to 150 s Only for relay contact output or SSR/SSC drive output only
Control cycle	0.5 s	0.5 s
Anti-reset windup	0 to 100% of measuring range Automatically validated at auto tuning	0 to 100% of measuring range Automatically validated at auto tuning
Hysteresis band	0 to 50% of measuring range For on/off action only	50% of measuring range common to heating and cooling sides, For on/off action only
Overlap dead band	_	±50% of heating side proportional band

#### Transfer output (option for PXR3)

No. of points	1
Туре	4–20 mA DC • Load resistance: ≤ 500 Ω • Accuracy: ±0.3%FS at 23°C • Resolution: ≥ 2000
Output cycle	500 ms
Contents	PV, SV, DV, MV

#### RS-485 communication (option for PXR3)

Modbus RTU or Z-ASCII, two-wire, half-duplex bit serial, asynchronous communication	
Serial characteris- tics	Data bits: 8 bits. Parity: odd, even, none Baud rate: 9600 bps
Connection	≤ 32 units, multi drop
Communication distance	≤ 500 m (total connection length)
Recommended RS-232C RS-485 converter	Isolated type Manufacturer: OMRON Co., Ltd. (Japan) Model: K3SC-10

	Other functions		
	Ramp soak (option)	2 program pattern of 4 steps each, or 1 program parttern x 8 steps On PXR3, a user can use the digital input to start/reset the ramp soak action.	
	Data backup at power outage	on non-volatile memory	
	Self-diagnosis	by watchdog timer	

#### Operation and storage conditions

Operating temperature	-10°C to 50°C
Storage tempera- ture	-20°C to 60°C
Humidity	≤ 90% RH (no condensation)

#### Measurement range

Input signal		Range(°C)	Range(°F)
RTD	Pt100	-150 to 850*	-238 to 1562
	J	0 to 800	32 to 1472
	K	0 to 1200	32 to 2192
	R	0 to 1600	32 to 2912
Thermocouple	В	0 to 1800	32 to 3272
	S	0 to 1600	32 to 2912
	Т	-150 to 400	-238 to 752
	E	-150 to 800	-238 to 1472
	N	0 to 1300	32 to 2372
	PLII	0 to 1300	32 to 2372
DC voltage	1 to 5V	scaling range	-1999 to 9999
DC current	4 to 20mA	scaling range -1	

- For 4–20 mA current input, add the provided 250-ohm resistor to the input terminal.

  For temperatures of 1000°C (1832°F) or above, the decimal point does not appear on the display.
- By editing the parameter, you can switch the input type setting among RTD and thermo-couples, or between voltage and current.

## Ordering Code

	PXR 3 2 - 9 10 11 12	13 14 F
Digit	Specification	Code
4	<front dimensions="" h="" w="" x=""></front>	
-	48 × 24 mm	3
5	<input signal=""/> Thermocouple °C Thermocouple °F RTD Pt100 Ω 3-wire °C RTD Pt100 Ω 3-wire °F 1 to 5 V DC 4 to 20 mA DC	T R N S A B
6	<control 1="" output=""> Relay contact output SSR/SSC driving output 4 to 20 mA DC output</control>	A C E
7	<control 2="" output=""> None Relay contact output*<sup>1</sup> SSR/SSC driving output*<sup>1</sup> 4 to 20 mA DC output*<sup>1</sup></control>	Y A C E
8	<revision code=""></revision>	2
9	<option 1=""> None Alarm 1 point Ramp soak Alarm 1 point + ramp soak Alarm 2 points*<sup>2</sup> Alarm 2 points + ramp soak*<sup>2</sup></option>	0 1 4 5 F G
10	<instruction manual=""><power supply="" voltage="">         None       100 to 240 V AC         English       100 to 240 V AC         None       24 V AC/DC         English       24 V AC/DC         <option 2=""></option></power></instruction>	N V C B
12	None RS-485 Modbus interface RS-485 Z-ASCII interface Transfer output + Digital input 1 point*3	000 M00 N00 Q00
13	Transfer output*s Digital input 2 points RS-485 Modbus interface + Digital input 1 point RS-485 Z-ASCII interface + Digital input 1 point	R00 T00 V00 W00

14 Non-standard parameter setting

\*1:Incompatible with two alarms specification (9th code "F" and "G").

\*2:Incompatible with two control outputs specification (7th code "A", "C", and "E").

\*3:Incompatible with two control outputs (7th code "A", "C", and "E"), two alarms (9th code "F" and "G"), and 24 V power supply (10th code "B" and "C").

Separate order items	
DIN rail mounting adapter (for PXR3)	ZZR*CTK368715P1

	4	5	O	-	0		9	10	- 11	12	13	
PXR	4			S	1	] - [						

Digit	Specification	Code
4	<front dimensions=""></front>	
	48 × 48mm	4
	<input signal=""/>	
	Thermocouple °C	Т
	Thermocouple °F	R
5	RTD Pt100 3-wire type I (°C)*1	N
١	RTD Pt100 3-wire type I (°F)*1	S
	1 to 5V DC	Α
	4 to 20mA DC	В
	RTD Pt100 3-wire type II (°C)*2	W
	<control 1="" output=""></control>	
6	Relay contact output	Α
١	Voltage pulse output (24V DC)	С
	4 to 20mA DC output	E
7	<terminal></terminal>	
	Socket type	S
8	<revision code=""></revision>	1
	<option></option>	
	None	0
	Alarm 1point	1
9	Ramp soak	4
	Alarm 1point + ramp soak	5
	Alarm 2points	F
	Alarm 2points + ramp soak	G
	<instruction manual=""> <power supply="" voltage=""></power></instruction>	
	None 100 to 240V AC	N
10	English 100 to 240V AC	V
	None 24V AC/DC	С
	English 24V AC/DC	В
11	<socket></socket>	000
12	None TD40Y	000
	For rail mounting (8-pin) Type: TP48X	100
13	For panel mounting (8-pin) Type: TP48SB	200
	For rail mounting (11-pin) Type: TP411X	400
	For panel mounting (11-pin) Type: TP411SBA	500

#### Separate order items

0	770000 4 4400
Shunt resistor (250 O ±0.1%)	

#### Scope of delivery

Controller, panel mounting bracket, watertight packing, 250 ohm resistor(for current input), instruction manual

## Micro-Controller X

## PXE



48 × 48 × 63.5 mm

( (

### Simple and Easy

- 1.6-mm shallow and waterproof front panel
- A user can switch input type among Pt100 RTD and 9 types of thermocouples and their measuring range with front keys
- On-off, PID, and fuzzy control
- Relay contact output or SSR drive output
- Up to two alarm outputs





delicial	
Power supply voltage	100 V (-15%) to 240 V (+10%) AC, 50/60 Hz
Power consumption	100 V AC: ≤ 5 VA 220 V AC: ≤ 6 VA
Insulation resistance	≥ 20 MΩ (at 500 V DC)
Withstand voltage	Between the power supply and others: 1500 V AC for 1 min *SSR driving output is not isolated from input terminals.
Input impedance	Thermocouple: ≥ 1 MΩ
Allowable signal source resistance	Thermocouple: ≤ 100Ω
Allowable wire resistance	RTD: ≤10 Ω per wire
Input value correction	Process value shift: ±10% FS Input filter: 0 to 120.0 s settable in 0.1 s steps (first order lag filter)
Noise reduction ratio	Normal mode noise (50/60 Hz): ≥ 40 dB Common mode noise (50/60 Hz): ≥ 120 dB

#### Display and keys

Туре	LED
Keys	4 keys
Cotents	PV and SV: 4 digits, 7-segment Status indicator: control output, alarm, standby

#### Structure

Installation	Installation Panel flush mounting	
Electrical connection	M3 screw terminal	
Case	Plastic (non-combustible grade UL94V-0 equivalent) Color: black	
IP rating	Front waterproof structure: NEMA4X (IP66 equivalent) (When mounted on panel with our genuine packing. Waterproof feature unavailable in close mounting of multiple units.) Rear case: IP20	
Weight	Approx. 100g	

PV input	
No. of inputs	1
Signal	Thermocouples or RTD *See a separate table for measurement range.
Sampling rate	0.2 s
Indication accuracy (at 23°C)	(±0.5% of process value or 1°C whichever is greater) ±1digit±1°C •Thermocouple -100°C or less: (±2% of process value) ±1digit±1°C •Accuracy is not assured for ranges from 0 to 500°C for type R thermocouple and from 0 to 400°C for type B thermocouple.
Burnout	A user can select either the upper or the lower limit to which the control output should go when a sensor burnout occurs.

#### Control output 1

Control Cutput 1						
No. of points	1					
Туре	Select either of the followings:  •Relay contact (SPST-NO): 220 VAC / 30 VDC, 3A (resistive load) Electrical life: 100,000 operations (rated load) Minimum switching current: 100 mA (24 VDC)  •SSR drive (Voltage pulse): ON: 10.2–15 V DC  OFF: ≤ 0.5 V DC  Maximum current: 20 mA					

#### Alarm or control output 2 (option)

No. of alarms	≤ 2
Alarm type	Absolute alarm, deviation alarm, zone alarm with upper and lower limits for each Hold function available Alarm latch, excitation/non-excitation selecting function
Alarm ON-delay	0 to 9999 s, settable in 1 s steps
Contact	Relay contact: SPST-NO, 220 V AC/30 V DC, 1 A (resistive load) Electrical life: 100,000 operations (rated load) Minimum switching current: 100 mA (5 V DC) Output cycle: 0.2 s

<sup>\*</sup>In the heating and cooling dual control, the alarm output 1 functions as the control output 2.

#### Control

Control type	On-off, PID, fuzzy, two-degree-of-freedom PID
Parameters	
Proportional band (P)	0.1 to 999.9% of measuring range settable in 0.1% steps
Integration time (I)	0 to 3200 s settable in 1 s steps
Differential time (D)	0 to 999.9 s settable in 0.1 s steps
	Proportional action when I, D = 0.
Proportional cycle	1 to 150 s, settable in 1 s steps
Control cycle	0.2 s
Anti-reset windup	0 to 100% of measuring range Automatically validated at auto tuning
Hysteresis band	0 to 50% of measuring range For on-off action only

#### Other functions

Data backup at power outage	on non-volatile memory
Self-diagnosis	by watchdog timer

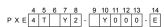
#### Operation and storage conditions

Operating temperature	-10°C to 50°C
Storage temperature	-20°C to 60°C
Humidity	≤ 90% RH (no condensation)

#### Measurement range

mode di oni oni i di igo								
Input signa	ıl	R	ange	(°C)				
RTD	PT1	-200	to	850				
NID	PT2	-199.9	to	500.0				
	J1	0	to	800				
	J2	0.0	to	400.0				
	K1	0	to	400				
	K2	-200	to	1200				
	K3	0.0	to	400.0				
	T1	-200	to	400				
Thermocouple	T2	-199.9	to	400.0				
	R	0	to	1600				
	В	0	to	1800				
	S	0	to	1600				
	Е	-200	to	800				
	N	0	to	1300				
	PL-2	0	to	1300				

## Ordering Code



Digit	Specification	Code
4	<front dimensions=""></front>	
4	48 × 48mm	4
5	<input signal=""/>	
3	Thermocouple, RTD Pt100 [°C]	Т
	<control output=""></control>	
6	Relay contact output	Α
	SSR drive output	С
7	-	Υ
8	<revision code=""></revision>	2
	<alarm output=""></alarm>	
9	1 point	1
9	2 points	2
	2 points (independent COM)	J
10	<instruction manual=""></instruction>	
10	Japanese/English/Chinese	Y

#### Scope of delivery

Controller, panel mounting bracket, watertight packing, instruction manual

#### Separate order item

Terminal cove	ZZPPXR1-A230

## **Digital Controller**

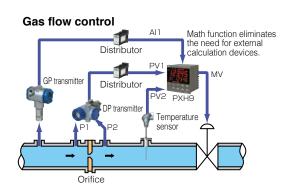
## **PXH**



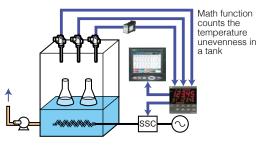


### High Speed and High Accuracy

- Fast sampling: 50 ms
- Reading accuracy: 0.1%
- 5-digit display can show hundredths place
- Universal input (up to 2 points)
- 9 DI + 9 DO
- 1 AI + 2AO
- Relay contact, SSR/SSC drive, 4-20 mA DC, or motor-operated valve control output
- 64 steps ramp soak function
- Math function
- Pre-installed program templates
- RS-485 communication



#### Multi-point measurement

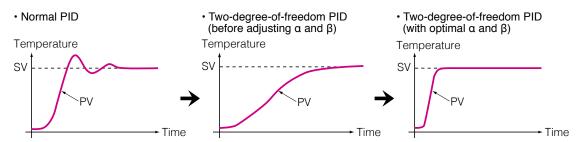




#### **Control Functions**

#### **Two-Degree-of-Freedom PID**

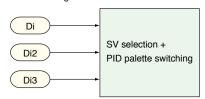
Suppresses overshoot and undershoot occurs at startup or at SV change, or due to disturbances.



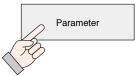
#### **PID Palette**

PID palette is pre-installed program templates that allow easy configuration for various applications. You can switch among seven palettes by the following three methods.

- Automatic switching according to PV
- SV switching

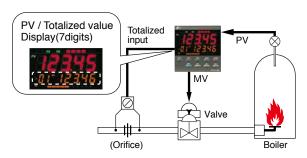


- Manually (by changing parameter)



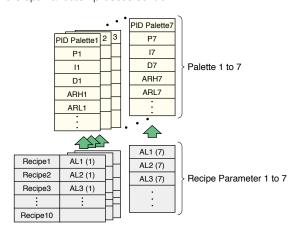
#### **Totalizer**

By combining the analog totalizer with the calculation function, you can obtain the flow rate after temperature and pressure compensation.



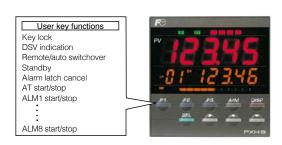
#### Recipe

A user can add up to 10 parameters to each PID palette. This allows more optimal batch process control.



#### **User Key**

PXH has three user keys to which you can allocate various functions





Control constraintible   100 V AC   1.5 V AC   V	General		Control output			
Power construction    No. of prices   Power construction   Power constru	Power supply voltage			Control output 1	Control output 2 (for heating and	
The state of the process of the proc	Power consumption		Maria Carabata	- Common Campar	cooling control)	
Pelay contact closure. SPC Control Control COVID-1997 (Control COV			No. of points	1	1	
International Control (1974)  **Action AD C** **Control Control (1974)  **Control (1974)  **Cont		Between the power source and other terminals: 1500 V AC for 1 min Between the relay output and other terminals: 1500 V AC for 1 min Others: 500 V AC for 1 min		Relay contact output: SPDT contact (DO4)     SSR/SSC driving output: Rating:		
Allowable page 1  Obligation (Control 1)  Description (Control 1)  Control (Control 1)  Contr	Input impedance	Current input: 250 Ω Voltage input: 1 MΩ  • Voltage input: 1 MΩ	Туре	4–20 mA DC     Motor-operated valve operation	• SSR/SSC driving output: Rating 12 V DC (10–15 V DC)	
resistance   Voltage input 1,0 14% per 900 (0)		Current input: ≤ ±25 mA		SPST-NO contact × 2 (with		
Allowable were residence or the processor of the processo			Control			
The second contract of			Control type			
**Sprace-cot estactor: OFF ocup point from 0.0 to 125.01% replactive day later to the 1900 to 150.00% corrected by straight limits occurred by straight limits.  Noise reduction ratio   Normal mode 180 dis (1908) Hot   Common mode 120 dis (1908) Hot   Common mode 1			Control mode	is available by key operation,		
Notice reduction ratio  Notice reduction ratio r	Input value correction	First-order lag filter: 0.0 to 900.0 s     Linearizer: Makes a line chart in which 16 data points are	Control template	allows a user to switch among the operation block and the I/O settings.		
Display and keys    Display   Display   Display	Noise reduction ratio	Normal mode: 40 dB (50/60 Hz)	Parameters	control type)	(Heating and cooling control type)	
Proportion of Fall = 0   Integral coperation OFF, All proposed   Proportion of Fall = 0   Integral coperation OFF, All proposed   Proportion of Fall = 0   Derivative operation OFF, All proposed   Proportion of Fall = 0   Derivative operation OFF, All proposed	Display and keys		Proportional band (P	(2-position) operation at P = 0		
Series   S			Integration time (I)		0.0 to 3200.0 s, Integral operation OFF at I = 0	
Parameter number. 7-segment, 2-digit Bar graph: 1-tespement   1o 150 s, For SSR/SSC driver	Keys	PV: 7-segment, 5-digit	Differential time (D)	0.0 to 999.9 s,	0.0 to 999.9 s,	
Status indicator: standby, control output, alarm, control mode  Structure  Installation  Panel mounting  Electrical connection  M3 screw terminal  Case Plastic, gray Plastic, gray Plastic, gray Prating  Equivalent to IP08 and NEMA 4X  Approx. 500 g  Approx. 500 g  PV input  No. of inputs  1 or 2  Signal Sampling rate S0% of measurement range, conditional only. PV variation ratio, incompleted in conditional only. PV variational ratio. P	Cotents	Parameter number: 7-segment, 2-digit	Proportional cycle		1 to 150 s, For SSR/SSC drive or relay output only	
Structure Installation   Panel mounting   Electrical connection   M3 screw terminal   Case   Plastic, gray   Prating   Equivalent to IP66 and NEMA 4X   Weight   Approx. 500 g   Prating   Equivalent to IP66 and NEMA 4X   Weight   Approx. 500 g   Prating   Equivalent to IP66 and NEMA 4X   Weight   Approx. 500 g   Provingual   No. of inputs   1 or 2   Signal   Thermocouples, RTD, voltage, or current   See a separate table for measurement range.  Sampling rate   Soms   Thermocouple (+0.1945 s-1digit =1*C) or ±1.5*C, whichever is larger   Indication accuracy   Intermocouple 6, 0-500°C range: ±5%FS ±1digit ±1*C   Thermocouple 7, 0-700°C range: ±5%FS ±1digit ±1*C   Thermocouple 6, 0-500°C range: ±5%FS ±1digit ±1*C   Thermocouple 7, 0-700°C ran						
Installation   Parel mounting   Parel mo	Structure		Anti-reset windup	-	0 to 100% of measurement range	
Prating   Equivalent to IP66 and NEMA 4X	Installation					
Praining   Equivalent to IP66 and NEMA 4X   Weight   Approx. 500 g				7	7	
Mo. of input					I.	
PV input  No. of linputs  1 or 2  Signal  Thermocouples, RTD, voltage, or current  See a separate fable for measurement range.  50 ms  Thermocouples (±0.1%FS ±1digit ±1°C) or ±1.5°C, whichever is larger  Indication accuracy (at 23°C)  Thermocouple B, 0-400°C range: ±5%FS ±1digit ±1°C  Thermocouple B, 0-400°C ra	•					
Signal   Thermocouples, RTD, voltage, or current	•			PV (H/L limit, absolute/deviation, b	pand), PV variation ratio, SV H/L	
Signal	No. of inputs					
Some   Some   Some   Some   Thermocouple: (±0.1%FS ±1digit ±1°C) or ±1.5°C, whichever is larger   Thermocouple B, 0-400°C range: ±5%FS ±1digit ±1°C   Thermocouple R, 0-500°C range: ±5%FS ±1digit ±1°C   Thermocouple R, 0-500°C range: ±1%FS ±1digit ±1°C   Thermocouple R, 0-500°C range: ±1%FS ±1digit ±1°C   Thermocouple input version or the RTD input version, a user can select either the upper or the lower limit to which the control output should go when a sensor burnout occurs.    In the thermocouple input version or the RTD input version, a user can select either the upper or the lower limit to which the control output should go when a sensor burnout occurs.    Digital input   No. of inputs   1		*See a separate table for measurement range.		To to 9999 S, O to 9999 Milli		
larger   l	Sampling rate			2 (DO3 & DO4) to 9		
Voltage, current: ±0.1%F/S ± ridigit		larger Thermocouple B, 0-400°C range: ±5%FS ±1digit ±1°C Thermocouple R, 0-500°C range: ±1%FS ±1digit ±1°C	Contact	SPDT contact (DO4) Contact capacity: 220 V AC / 30 V	DC, 1A (resistive load)	
Can select either the upper or the lower limit to which the control output should go when a sensor burnout occurs.    Digital input			Functions		alou loud)	
Digital input	Durnout		Transfer output			
Type   4-20 mA   Contents   PV, SV, MV, DV, AIM, MVRB, TV	DufflOut	· ·		≤ 2	-	
No. of inputs 4 to 9 Switch Volt-free contact or transistor Contact capacity 12 V DC, about 2 mA (per point) Imput pulse width ≥ 200 ms Control mode changeover, EX-MV selection, SV changeover, Control standby, Auto-tuning start, Timer start, Alarm latch cancel  Analog input (option)  No. of inputs 1  ■ DC voltage: 1-5 V DC, 0-5 V DC, 0-10 V DC ■ Valve position feedback signal (potentiometer): resistance range: 100Ω to 10ΚΩ, 3-wire    Valve position feedback signal (potentiometer): resistance range: 100Ω to 10ΚΩ, 3-wire    Other functions		a contract conducting the first a contract conduction.	Туре	4–20 mA		
Switch Volt-free contact or transistor  Contact capacity 12 V DC, about 2 mA (per point) Input pulse width ≥ 200 ms  Functions Control mode changeover, EX-MV selection, SV changeover, Control standby, Auto-tuning start, Timer start, Alarm latch cancel  Analog input (option)  No. of inputs 1  • DC voltage: 1-5 V DC, 0-5 V DC, 0-10 V DC • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  Power supply output for transmitter  No. of outputs 1  Rating 24 V DC (17-30 V DC)  RS-485 communication  Modbus RTU, two-wire, half-duplex bit serial, asynchronous communication  Serial characteristics  Serial characteristics  Connection ≤ 32 units  Communication distance  Sometion ≤ 32 units  Communication distance  Other functions  Ramp soak 64 step ramp soak with guaranteed soak Data backup at power outage  Self-diagnosis by watchdog timer  Math function Temperature and pressure compensation, average, H/L set		1	Contents	PV, SV, MV, DV, AIM, MVRB, TV		
Contact capacity Input pulse width  ≥ 200 ms  Functions  Control mode changeover, EX-MV selection, SV changeover, Control standby, Auto-tuning start, Timer start, Alarm latch cancel  Analog input (option)  No. of inputs  1  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC • Signal • Data backup at power outage  • Self-diagnosis • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC • Serial characteristics  Connection  Serial characteristics  Connection  ≤ 32 units  Communication distance  • 500 m (total connection length)  Other functions  Ramp soak • 4 step ramp soak with guaranteed soak  Data backup at power outage  Self-diagnosis by watchdog timer  Math function  Temperature and pressure compensation, average, H/L sections	· · · · · · · · · · · · · · · · · · ·		Power supply ou	tout for transmitter		
Input pulse width   2 200 ms  Control mode changeover, EX-MV selection, SV changeover, Control standby, Auto-tuning start, Timer start, Alarm latch cancel  Analog input (option)  No. of inputs  1				1		
Functions  Control mode changeover, EX-MV selection, SV changeover, Control standby, Auto-tuning start, Timer start, Alarm latch cancel  Analog input (option)  No. of inputs  1  DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  PC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  PC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  PC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  PC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  Connection  Serial characteristics  Data bits: 8 bits. Parity: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Sommunication distance  Communication distance  Serial characteristics  Data bits: 8 bits. Parity: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Sommunication distance  Serial characteristics  Data bits: 8 bits. Parity: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Sommunication distance  Serial characteristics  Data bits: 8 bits. Parity: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Sommunication distance  Serial characteristics Data bits: 8 bits. Parity: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Sommunication distance  Serial characteristics Data bits: 8 bits. Parity: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Sommunication distance  Serial characteristics Data bits: 8 bits. Parity: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Sommunication distance  Serial characteristics Data bits: 8 bits. Parity: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Sommunication distance  Serial characteristics Data bits: 8 bits. Parity: odd, even, none Baud rate: 9600 bps, 19200 bps, 1	•	N 1 /	•	24 V DC (17–30 V DC)		
Modbus RTU, two-wire, half-duplex bit serial, asynchronous communication  No. of inputs  1 Dt voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10ΚΩ, 3-wire  Communication distance  Serial characteristics  Party: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Communication distance  Serial characteristics  Communication distance  Serial characteristics  Communication distance  Serial characteristics  Communication  Communication  Communication  Serial characteristics  Party: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Serial characteristics  Communication  Serial characteristics  Party: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Serial characteristics  Party: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Serial characteristics  Party: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Serial characteristics  Communication  distance  Serial characteristics  Party: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Serial characteristics  Serial characteristics  Party: odd, even, none Baud rate: 9600 bps, 19200 bps, 38400 bps  Connection  Serial characteristics  Serial charac	•	Control mode changeover, EX-MV selection, SV changeover,				
No. of inputs    OC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC     Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire    OC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC     Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire    OC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC     Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire    Connection     Serial characteristics     Connection     ≤ 32 units     Communication distance     Sommunication     Communication     Sommunication     Expression     Other functions     Other funct	Amalam brook ( )			hit covial counch	ation	
Pode voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • DC voltage: 1–5 V DC, 0–5 V DC, 0–10 V DC  • Valve position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • So 0 m (total connection length)  • So 0 m (total connection length)  • Other functions  • A sequence of the position feedback signal (potentiometer): resistance range: 100Ω to 10KΩ, 3-wire  • So 0 m (total connection length)	<u> </u>	uon)		•		
Signal   Valve position feedback signal (potentiometer): resistance range:   Connection   ≤ 32 units	No. of inputs	PC voltage: 1 EV DC 0 EV DC 0 10 V DC	Serial characteristics			
Continue   South (lotal connection length)	Signal	Valve position feedback signal (potentiometer): resistance range:		≤ 32 units		
Ramp soak 64 step ramp soak with guaranteed soak  Data backup at power outage on non-volatile memory  Self-diagnosis by watchdog timer  Math function Temperature and pressure compensation, average, H/L se			distance	Sour m (total connection length)		
Data backup at power outage on non-volatile memory  Self-diagnosis by watchdog timer  Math function Temperature and pressure compensation, average, H/L se				64 stop rome cook with	d soak	
outage on non-voiatile memory  Self-diagnosis by watchdog timer  Math function Temperature and pressure compensation, average, H/L se			· ·		u soak	
Math function Temperature and pressure compensation, average, H/L se			outage	-		
					ensation, average. H/L selector	
input switching, etc.			Math function	input switching, etc.	. ,	

Humidity

Operation and storage conditions
Operating temperature -10°C to +50°C
Storage temperature -20°C to +60°C

≤ 90% RH (no condensation)

### **Ordering Code**

										12	
Basic Type	Р	Χ	Н	9	Α		1	] -	٧		0

	**		
Digit	Specification	on	Code
4	<front dimensions=""> 96 x 96 mm</front>		9
5	<number control="" function="" loops="" of=""> 1-loop basic controller</number>		А
6	<pv input=""> 1 point 2 points*1</pv>		1 2
7	<analog input=""> None DC voltage: 1 point</analog>		0
8	<revision code=""></revision>		1
9	Output>*3    OUT1    Current    Current    Current    SSR/SSC driver    SSR/SSC driver	OUT2  None Current Transmitter supply None Current	1 2 5 A B
10	<power supply=""> 100 to 240 V AC</power>		V
11	<communication interface=""> None RS-485</communication>		0 R
12	<digital and="" input="" output="">*1.2 DI 4 4 9</digital>	DO 2 4 9	— 0 A B
13	<additional specifications=""> None</additional>		0

- \*1:The 6th code "2" (2 inputs) and the 12th code "B" (9 DI and 9 DO) are not compatible.
  \*2:When you use a relay for the control output 1, the terminal DO4 is allocated to it.
  \*3:See the matrix on the right side for the function of each output.

	Terminal	DO4	OL	OL	IT2	
	Output Kind	Relay	Current (4 to 20 mA)	SSR/SSC driver	Current (4 to 20 mA)	Transmitter
	Function*	Control output	Control output or		Transfer	power
Code		or Digital output	Transfer output	Control output	output	очрр.,
9th	1	✓	✓			
digit	2	✓	✓		1	
	5	1	1			1
	Α	✓		1		
	В	✓		1	✓	

<sup>\*</sup> If there are two functions listed, a user can select the function by parameter setting.

#### P X H 9 F 11 - V 0 **Heating/Cooling Control Type**

Divis.	0		0
Digit	Specificati	on	Code
4	<front dimensions=""> 96 x 96 mm</front>		9
5	<number control="" function="" loops="" of=""> 1-loop heating/cooling controller</number>		F
6	<pv input=""> 1 point 2 points*1</pv>		1 2
7	<analog input=""> None DC voltage: 1 point</analog>		0
8	<revision code=""></revision>		1
9	<pre><output>*3     OUT1     Current     Current     Current     Current     SSR/SSC driver     SSR/SSC driver     SSR/SSC driver</output></pre>	OUT2  None Current SSR/SSC drive Transmitter supply None Current SSR/SSC drive	1 2 3 5 A B C
10	<power supply=""> 100 to 240 V AC</power>		V
11	<communication interface=""> None RS-485</communication>		0 R
12	<digital and="" input="" output="">*12 DI 4 4 9</digital>	DO 2 4 9	- 0 A B
13	<additional specifications=""> None</additional>		0

- \*1:The 6th code "2" (2 inputs) and the 12th code "B" (9 DI and 9 DO) are not compatible.

  \*2:When you use one relay for the control output, the terminal DO4 is allocated to it. When you use two relays for the control output 1 and the control output 2, the terminal DO3 and DO4 are allocated respectively.

  \*3:See the matrix on the right side for the function of each output.

#### Scope of delivery

Controller, mounting bracket, watertight packing, unit label, terminating resistor (for version with RS-485 communication only), instruction manual

Motorized Valve Control Type P X H 9   1   -   9   10   11   12					
Digit	Specification	Code			
4	<front dimensions=""> 96 x 96 mm</front>	9			
5	<number control="" function="" loops="" of=""> 1-loop motorized valve controller (with valve position feedback input) 1-loop motorized valve controller (without valve position feedback input)</number>	D S			
6	<pv input=""> 1 point 2 points*1</pv>	1 2			
7	<analog input=""> None DC voltage: 1 point</analog>	0			
8	<revision code=""></revision>	1			
9	<output>*2 OUT1 OUT2 Current None Current Current Current Transmitter supply</output>	1 2 5			
10	<power supply=""> 100 to 240 V AC</power>	V			
11	<communication interface=""> None RS-485</communication>	0 R			
12	<pre><digital and="" input="" output="">*1.3 DI DO 4 2 4 4 9 9 9</digital></pre>	0 A B			
13	<additional specifications=""> None</additional>	0			

- \*1:The 6th code "2" (2 inputs) and the 12th code "B" (9 DI and 9 DO) are not compatible. Select "2 points" when a remote SV input (RSV) is required.
  \*2:"D" for the 5th digit and "1" for the 7th digit cannot be specified at the same time.
  \*3:DO4 is used as control output. If 2 or 3 DO points are required for event output, specify the code A, and if 4 to 8 DO points are required, specify the code B.

	Terminal	DO4	OUT1	OL	JT2	
	Output Kind	Relay	Current (4 to 20 mA)	Current (4 to 20 mA)	Transmitter	
Code	Function*	Valve control output	Transfer output	Transfer output	power supply	
9th	1	✓	1			
digit	2	✓	1	1		
	5	✓	✓		✓	

<sup>\*</sup> If there are two functions listed, a user can select the function by parameter setting.

	Terminal	DO3	DO4	OU	T1	OU	T2	
	Output Kind	Relay	Relay	Current (4 to 20 mA)	SSR/SSC driver	Current (4 to 20 mA)	SSR/SSC driver	Transmit-
Code	Function*	Control output or Digital output	Control output or Digital output	Control output or Transfer output	Control output	Control output or Transfer output	Control output	ter power supply
9th	1	<b>✓</b>	1	1				
digit	2	<b>✓</b>	✓	<b>✓</b>		<b>*</b>		
uigit	3	✓	✓	<b>/</b>			✓	
	5	<b>✓</b>	<b>✓</b>	<b>✓</b>				<b>✓</b>
	Α	✓	<b>✓</b>		<b>√</b>			
İ	В	<b>✓</b>	1		1	1		
	С	✓	✓		✓		✓	

<sup>\*</sup> If there are two functions listed, a user can select the function by parameter setting.

Measurement range					
Innut oil	anal	Rang	Deselution (°O)		
Input sig	gnai	Max.	Min.	Resolution (°C)	
RTD Pt100		-150 to 850	0 to 150	0.01	
Thermocouple	J	0 to 1000	0 to 400	0.1	
	K	0 to 1200	0 to 400	0.1	
	R	0 to 1600	0 to 1600	0.1	
	В	0 to 1800	0 to 1800	0.1	
	S	0 to 1600	0 to 1600	0.1	
	T	-200 to 400	-200 to 200	0.1	
	E	-200 to 800	0 to 800	0.1	
	PR40/20	0 to 1800	0 to 1800	0.1	
	N	0 to 1300	0 to 1300	0.1	
	PL-II	0 to 1300	0 to 1300	0.1	
	WRe5-26	0 to 2300	0 to 2300	0.1	
DC voltage	1 to 5 V				
	0 to 5 V				
	0 to 10 V	-19999 t	o 99999	1/10000	
	0 to 10 mV	(Range wh	ere scaling	digit	
	0 to 50 mV	is allo	owed)	digit	
DC current	4 to 20 mA		*		
	0 to 20 mA				
Motorized valve position feedback	Potentiometer	100 to	o 10 k	1/1000 digit	

#### Separate order items

Terminal cover	ZZP PXR1-B230	Two pieces are necessary per unit.
PC loader interface cable	ZZP PXH1*TK4H4563	For RS-232C Interface

## Multi-Loop Module Type Temperature Controller

## **PUM**









- Control Module
- Event Input/Output
- Analog Input/Output
- Analog Input
- Analog Output
- CC-LINK
- Programless Communication with Mitsubishi PLC
- PROFIBUS
- Ethernet

#### Smart!

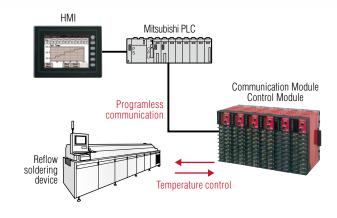
- Up to 64 loops (4 loops × 16 units)
- Heater break alarm by using CT, up to 8 points
- · Communication with PLC

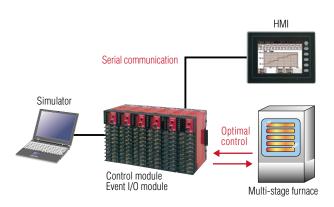
#### Easy!

- Detachable terminal
- Easy-to-use software
- · Easy mounting onto DIN rail

#### Fast!

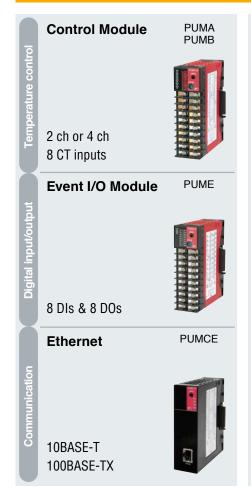
- High-speed data transmission (RS-485 / 115.2 kbps or 230.4 kbps)
- · Sampling time: 200 ms

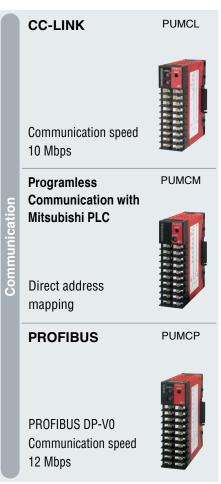


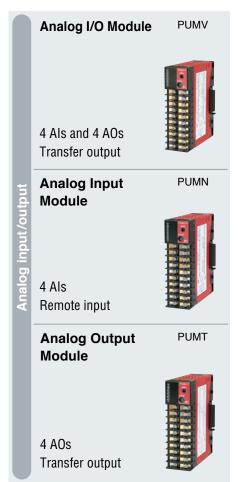




#### **Variations**

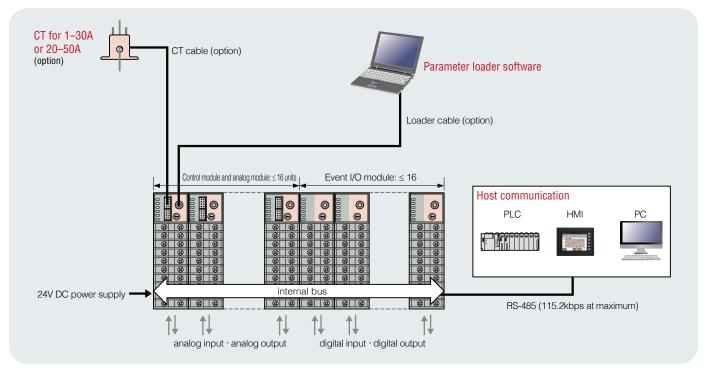






### System Configulation Example

- · Control module (PUMA, PUMB) + analog I/O module (PUMV, PUMN, PUMT): up to 16 units in total
- · Event I/O module (PUME): up to 16 units



# Digital Thermostat PXR3



## Temperature Alarm with On-Off Contact Output Ideal for Overheat Detection

- Thermocouple input or thermistor input
- Waterproof front panel: IP66 and NEMA 4X equivalent
- Up to two alarm outputs (H, L, HH, LL alarm available)
- Alarm setting in 1°C steps
- Panel mounting
- DIN rail mounting or wall mounting with optional adapter
- · Lightweight 150 g
- Simple operation with three front keys
- European-style terminal



Power supply voltage	100 (-15%) V to 240 (+10%) V AC, 50/60 Hz
	Power consumption: ≤ 6 VA (at 100 V AC), ≤ 8 VA (at 240 V AC),
	Number of inputs: 1 Input signal and measurable range: see Table 1. Allowable signal source resistance: thermocouple input $\leq$ 100 $\Omega$ Measurement cycle: $\leq$ 2 seconds
Input	Burnout function (open-circuit detection): you can set the output upon an open-circuit to the upper limit or the lower limit Input impedance: thermocouple input $\geq 1~\text{M}\Omega$ Input filter: first-order lag filter, configurable in 0.5-second steps, within 0-90 seconds Input compensation: configurable within $\pm 10\%$ of measurement range
Display and keys	Green LED 7-segment 4-digit alphanumeric display Display contents: measured value, alarm 1 setpoint, alarm 2 setpoint, parameter name, parameter value 3 keys, with key lock function
Accuracy	Indication accuracy: See Table 1 (Error of temperature sensor is not included)  Reference junction compensation accuracy: ±1°C (at 23°C)
Alarm output	SPST-NO contact, 1 or 2 points Contact capacity: 220 V AC / 30 V DC, 1A (resistive load) Mechanical life of contact: 10 million times (no load) Electrical life of contact: 100 thousand times (rated load)  Output cycle: 0.5 seconds  Alarm type: (high or low absolute alarm, hold function available) Alarm setpoint: configurable in 1°C steps, within 0–100% of measurement range Hysteresis: configurable in 1°C steps, within 0–110% of measurement range Alarm delay: configurable within 0–120 seconds
Operating conditions	Ambient temperature: -10°C to +50°C Ambient humidity: ≤ 90% RH (no condensation)
Installation	Panel mount, or DIN rail or wall mount when using DIN rail mounting adapter (separate order item)
Electrical connection	European-style terminal
Case	Plastic (equivalent to non-combustibility grade UL94V-0), black
IP rating of front panel	IP66 (equivalent to NEMA 4X) When installed with our genuine waterproof packing.
Weight	Approx. 150 g

#### Measurement range

Sensor		Range (°C)	Indication accuracy
	J	0 to 800	±0.5% FS ±1digit ±1°C
	К	0 to 1200	±0.5% FS ±1digit ±1°C
Thermocouple	R	0 to 1600	±0.5% FS ±1digit ±1°C
	Т	0 to 400	±0.5% FS ±1digit ±1°C
	E	0 to 600	±0.5% FS ±1digit ±1°C
Thermistor	PB-36	0 to 100	±4°C

#### Notes:

- Notes:

   The thermostat cannot deliver the accurate indication when the sensor is the type R thermocouple and the temperature is in the range between 0 and 500°C.

   You cannot switch the input type between the thermistor and the thermocouple. You can switch the input type among the five type of thermocouples by using the front keys.

   If you change the input type, be sure to change the measurement range setting accordingly.

   The indication accuracy of thermocouple does not include the reference junction compensation error (±1°C).

- The indication accuracy of thermistor does not include the error of sensor.

#### Ordering code

Sensor		Number of alarms	Model code
Thormoounlo	Not provided	1	PXR3TAY2-0V061
Thermocouple		2	PXR3TAY2-1V061
Thermistor	Provided	1	PXR3HAY2-0V061
THEITHISTOL		2	PXR3HAY2-1V061

#### Scope of delivery

Thermostat, panel-mounting adapter, front waterproof packing, instruction manual \*For the thermistor input version, a thermistor sensor is additionally provided.

#### Separate order item

DIN rail adapter	ZZP*CTK368715P1

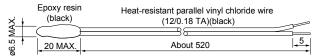
#### **Default setting**

Measurement range Type K thermocouple: 0°C to 1200°C Thermistor: 0°C to 100°C	
Alarm setpoint  Type K thermocouple, 1 alarm: upper limit 1200°C Type K thermocouple, 2 alarms: lower limit 0°C, upper limit 17hermistor, 1 alarm: upper limit 100°C Thermistor, 2 alarms: lower limit 0°C, upper limit 100°C	
Alarm hysteresis width 1°C	
Alarm delay time	0 seconds
Indication	Measured value
Burnout	Upper limit
Input filter	5 seconds
Input value compensation	0%

#### Attached thermistor sensor

Measurement range	0°C to 100°C
Constant $\beta$	3990 K
Nominal resistance	6 kΩ (°C)
Lead wire	Heat-resistant vinyl chloride, black, 520 mm, Temperature range: -20°C to +105°C
Accuracy	≤ 2°C

#### Dimensions (unit: mm)



#### Thermistor sensor for replacement

ZZP\*CTK7L3941P1

Please read the following instructions carefully before operating the Digital Temperature Controller

## **AWARNING**

#### **Over-Temperature Protection**

Any control system design should take into account that any part of the system has the potential to fail.

For temperature control systems, continued heating should be considered the most dangerous condition, and the machine should be designed to automatically stop heating if unregulated due to the failure of the control unit or for any other reason.

The following are the most likely causes of unwanted continued heating:

- 1) Controller failure with heating output constantly on
- 2) Disengagement of the temperature sensor from the system
- 3) A short circuit in the thermocouple wiring
- 4) A valve or switch contact point outside the system is locked to keep the heat switched on.

In any application where physical injury or destruction of equipment might occur, we recommend the installation of independent safety equipment, with a separate temperature sensor, to disable the heating circuit in case of overheating.

The controller alarm signal is not designed to function as a protective measure in case of controller failure.

Information in this catalog is subject to change without notice. Read the instruction manuals thoroughly before using the products.



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